Design and Functioning of Automated Medicine Dispensing Module

Kunal Agrawal, Jil Jain, Vrutant Shah, Gargi Chauhan, Piyush Surani

ere technology has bridged the gap ing to reducing human efforts and problem that major hospitals & Staff & resources. As per the survey adia faces a significant shortage in commonly used medicines was collected and analyzed as

commonly used medicines was collected and analyzed as shown in the Table 1. The medicines were chosen as per the suggestion of doctors and pharmacists. The various shapes of medicines helped in building the dispensing module for universal height based medicines. Upon drawing inferences from the data collected, the project was initiated by analyzing past research papers and identified that focus was kept on the electronics part of the machine and not on the mechanical aspect. The medicinal data was bifurcated in terms of different standards shapes as follows: Cube, Oval (With height present & absent- This indicates the pills which are spherical or have minimal height), Cylindrical & Round.

store and also help in maintaining sanitary standards.

Table -1: Medicinal Data

CUBE							
Max Length	21.2m m	Min Length	11.2m m	Comm on Range Length	17-18mm	Remar k	Every size of medicin e is present betwee n commo n length, breath and height.
Max Breath	10mm	Min Breath	6.6mm	Comm on Range Breath	8-10mm		
Max height	9mm	Min Height	4.9mm	Comm on Range Height	5-6mm		
Averag e Length	17.48m m	Averag e Breath	8.43m m	Averag e Height	7.61mm		
Total Number of Medicine					39 (35.77%)		
OVAL(HEIGHT PRESENT)							
Max Length	14.6m m	Min Length	11.3m m	Comm on Range Length	14.3-14.6 mm	Remar k	3 medicin e are present in commo n Range
Max	11.6m	Min Breath	7mm	Comm on Range	N/A		
Breath	m	Dieatii		Breath			Range Length.

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Abstract: In a world where technology has bridged the gap between people communicating to reducing human efforts and improving efficiency, the problem that major hospitals & pharmacies face is i.e. lack of staff & resources. As per the survey conducted by LANCET^[1], India faces a significant shortage in medical staff which leads to patients being unattended for several hours. This problem can be solved if the tasks per staff member is reduced and one such way is by reducing their repetitive movement from the patient's room to the pharmacy for giving the medicines to the patient. This effort can be reduced by creating a remotely located machine which can be placed at the right place to dispense medicines automatically. This reduces the extra movements and hence provides them the time to do tasks that are of more importance. Although the concept of an automated medicine dispensing unit is not new, it is something that if built and implemented, can provide aid to patients in developing countries.

Keywords: Height Adjustment Part, Hopper mechanism, Medicinal Data Analysis, Medicine Dispensing Module, Spring Slider Mechanism.

I. INTRODUCTION

This project was aimed to build a machine which provides medicinal aid to patients in a hospital. Upon observing and understanding the current progress in the field of pharmacy automation and going through past researches, the objectives were set to create a user friendly, compact & ease-to-use automated dispensing unit for medicines. The Machine includes loading/unloading mechanism & hopper mechanism for dispensing of medicines which includes sensors, servo motors, motor drivers, & Raspberry Pi 3 which help in keeping track of medicines being dispensed. The entire operation of this machine will be done automatically once the medicines are loaded and after being dispensed, the medicines will be packaged in a sanitized way which will help in reducing the unnecessary crowd around pharmacy

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Averag e Length	13.65m m	Averag e Breath	31.02m m	Averag e Height	5.25mm		differen t Breath. 2 medicin e are present in Comm on Range Height.	
Total Number of Medicine					5 (4.58%)			
	OVAL(HEIGHT ABSENT)							
Max Diamet er	10.4m m	Min Diamet er	7mm	Comm on Range Diamet er	N/A	Remar k	All 5 medicin e are of differen t Diamet er and Length.	
Max Length	22mm	Min Length	12.6m m	Comm on Range Length	N/A			
Averag e Diamet er	9.86m m	Averag e Height	13.96m m		N/A			
Total Number of Medicine					5 (4.58%)			
			CYLIN	DRICAL				
Max Diamet er	7.4mm	Min Diamet er	5.9mm	Comm on Range Diamet er	6mm		6mm Diamet er medicin e is most commo n as 4 medicin	
Max Height	21mm	Min Height	17mm	Comm on Range Height	17-17.5m m	Remar k		
Averag e Diamet er	6.2mm	Averag e Height	17.87m m		N/A		e are present out of 9.	
Total Number of Medicine 9 (8.25%)								
			RC	UND				
Max Diamet er	14.9m m	Min Diamet er	5mm	Comm on Range Diamet er	12-12.9m m 7-7.7mm 9.2-9.8mm		Most of the medicin e are present	
Max Height	6.3mm	Min Height	2.2mm	Comm on Range Height	3-4.8mm	Remar k	in Comm on Range Diamet	
Averag e Diamet er	7.52m m	Averag e Height	1.86m m	N/A			er as well as in Comm on Range Height.	
Total Number of Medicine 51 (46.78%)								

III. DESIGN AND FUNCTIONING OF MEDICINE DISPENSING MODULE

The key to this project is the development of the Dispensing Module. The Module has 3 major components: The body, slider-spring mechanism and height adjustment part. The medicines are inputted manually into the storage chamber from the top lid. Based on the height of the medicine, the height is adjusted and the adjustment part is

Retrieval Number: 100.1/ijeat.D23880410421 DOI:10.35940/ijeat.D2388.0410421 Journal Website: <u>www.ijeat.org</u> locked. Once the medicines are stored, the medicine that is placed in the slot at the bottom of the module is displaced towards the opening at the bottom by the slider spring mechanism which is controlled by a motor. The built prototype is shown in figures 1 & 2 along with detailed cross sectional modules shown in figure 3. A detailed part description of figure 3 is explained as follows:

1-Storage Chamber Opening: Opening to input medicines into the module.

2-Medicine

3-Storage Chamber: Space to store medicines under suitable storage conditions and providing isolation around the chamber.

4-Medicine Slot: Slot where medicines will fall under gravity and be placed for further dispensing.

5-Motor Attachment Slot: Space for adding extension slit which will provide sliding motion to the slider.

6-Slider: Part which moves sideways to shift medicine from Medicine slot to exit slot.

7-Exit Slot: Slot through which medicine will be dispensed out of the module.

8-Spring: Spring adds a balancing part for smooth movement of slider.

9-Hight Adjustment Part: Part used for adjusting size of module as per the height of medicine.



Fig.1: Images of Prototype

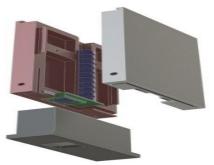


Fig. 2: Exploded view of Design



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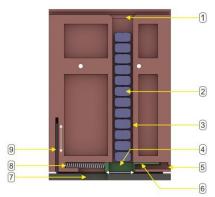


Fig. 3: Cross-section of Design

IV. FLOW OF OPERATIONS

The Machine is given input of prescribed medicines by a doctor via a computer interface and the signal is sent to a microcontroller which verifies the availability of medicines in the Dispensing module and upon verification, a signal is sent to the motor driver connected to the motors which are attached to the dispensing module for dispensing medicines as per the prescription. While being dispensed, the medicines are counted using sensors and upon reaching the counter as per the prescription, the motor stops movement and dispensing of medicines is halted. Post dispensing of medicines, they are packaged in cylindrical vials placed at the exit end of the machine and the vials are later collected by the user. The flow of operations is explained using Flowchart 1. Flow of Operations:

Step 1: User inputs data through computer

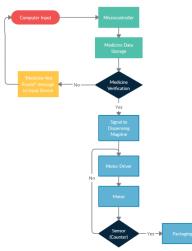
Step 2: Input is sent to the Microcontroller where it is verified with Medicine Data in dispenser

Step 3: Post verification, signal is sent to Dispensing Module for initiating the process.

Step 4: The signal is further sent to Motor Driver which actuates the motor which in turn moves the slider to dispense medicine.

Step 5: The medicines keep dispensing until the counter reaches its limit.

Step 6: Lastly the medicine is packaged and received by the user



Flowchart 1: Flow of Operations

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V.	HARDWARE COMPONENTS
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Component	Use
Servo Motors	Used in providing motion to Slider-Spring
	Mechanism. These are attached with a slit
	which is connected to the slider.
Motor Drivers	Motor Drivers receive signal from
	microcontroller to dispense medicines by
	movement of the motor which in turn
	moves the slider.
Object	Used for counting medicines coming out
Detection	of exit slot.
Sensor	
Medicine	Module for storing and dispensing
Dispensing	medicines.
Module	
Raspberry Pi 3	Used for handling operation of entire
	machine.

VI. RESULT AND DISCUSSION

The design of module was completed and prototypes prepared were well functioning. The Machine successfully dispenses medicines of varying height using a similar module. the slider-spring mechanism provided a good alternative to drop mechanism and helped in keeping a count of medicines being dispensed, also ensuring that medicines flow without getting stuck in storage space. Overall the machine worked as expected and provided insights for improvement.

VII. CONCLUSION

The project design and implementation lead to find solution for automating processes in pharmacies and providing prescribed medicines to patients automatically. The medicine dispensing module solves the problem of storing and dispensing of medicines of different heights and on implementing, the machine will provide aid to patients and medical staff in a hospital.

Future Scope:

The machine can be modified to become storage and dispensing unit for injections and can improve pharmacy automation.

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AUTHORS PROFILE



Kunal Agarwal, is a B.Tech student of Mechanical Engineering Department of Indus University of Technology, Ahmedabad, Gujarat. He has prominently participated in departmental workshops, non-technical events and been an eager student who seeks knowledge about the basic functioning of different

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Jil Jain, is a B.Tech student of Mechanical Engineering Department of the Indus University of Technology, Ahmedabad, Gujarat. The unique quality of his is a tendency to go beyond the syllabus. As an example of it, he prominently participated in numerous technical events, workshops during his bachelor's study. He

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Vrutant Shah, is a B.Tech student of Mechanical Engineering Department of Indus University of Technology, Ahmedabad, Gujarat. During the four years of his course, he has prominently participated in Technical fests, departmental workshops and been an eager student who seeks knowledge about the basic

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Gargi Chauhan, is a B.Tech student of Mechanical Engineering Department of Indus University Ahmedabad, Gujarat. She has participated in theoretical as well as practical sessions with an equal fervour and have enhanced her knowledge in machine optimization and product designing. She has attended several workshops and participated in co-curricular activities. She was also a part of

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Piyush Surani, has completed Bachelors of Engineering in Mechanical Engineering and Masters of Engineering in Computer Aided Design And Manufacturing. He is currently Assistant Professor in Indus University, Ahmedabad, Gujarat. He has published 5 research paper

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