

Design and Material Selection of Screw Feeder of Injection Molding Machine

Nimish Joshi, Prajakta Hambir, Pranav Karande, Swaraj Gurav, Venugopal Kulkarni

Abstract: The efficiency of the 'Injection molding Machine' lies in the proper designing of screw feeder mechanism. The screw feeding mechanism needs to be setup differently for different materials, molds etc. The proper design includes the work from selecting the appropriate materials, designing for the optimum design, analysis of the designed parts at different flow rates, speed and temperatures. There are various parameters that govern the efficiency of the 'Injection molding Machine'. These parameters include 'Filling Pressure', 'Mold Surface Temperature', 'Raw Material Melting Temperature', 'Filling Time' etc.

Keywords: Injection Mounding Machine, Screw Feeder Optimization, Materials Selection, Filling time

I. INTRODUCTION

Injection Molding Machine are known for their adaptability in manufacturing sector. It can be used for mass production and obtaining highly precise manufactured parts.

Injection molding is a method of manufacturing a plastic product from powdered thermoplastics by supplying the material through hopper to a heated chamber in order to make it easy to mold and force the material into the mold by the using the screw. In this whole process pressure should be persistent till the material is hardened and is ready to be detached from the mold. This is the most common and preferred way of producing a plastic products with any complexity and size.

The injection molding process

The stages of injection molding process are as follows

- 1. Polymer is feed through hopper to barrel
- 2. It is heated to a sufficient temperature to make it flow
- 3. The molten plastic which got melted will be injected under high pressure into the mold

This process combined is known as Injection. After injection pressure is applied to both plates i.e. fixed and moving plates of the injection molding machine in order to hold the mold tool together afterwards the product is set to cool which helps it in the solidification process.

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After the product gets its shape the two plates will proceed away from each other in order to detach the mold tool which is known as mold opening and finally the molded product is ejected or removed from the mold. And the process will get repeated. The molding cycle gets started with the recantation of the ejector plate, followed by shutting of the mold. The polymer resin is melted and injected into the mold by the injection unit. Hydraulically operated plunger is used to push the plastic through a heated region. The melt gets converged at a nozzle and is injected into the mold.

The melt is imposed into the mold in two stages:

- 1. The mold cavities are filled with molten resin. As the material is imposed forward, it gets passed over a spreader (torpedo), within the barrel resulting in mixing. This stage is determined by the rate injection velocity, pressure and time. Injection velocity is defined as the rate at which the plunger gets move forward.
- 2. Hold stage is started when no more material can be forced into the mold and where melt can still leak back through the gate. Forces are applied against the material in the cavity until the gate freezes to avoid leaking of the melt. In some machines, pack and hold are combined into a single holding stage.

Parts to be injection molded must be very attentively designed to make the molding process smoother; the material used, the desired shape and attributes of the part, the material of the mold, and the properties of the molding machine must all be taken into consideration. Each stage is controlled by a specific pressure and time span. Once the mold is filled and the gate gets cooled, the injection molding machine switches to the cooling stage. The cooling time decides the amount of cooling. After the cycle gets completed and before the next cycle can be run, the machine must be checked and get clearance as per directions in the manual.[7]

Problem statement

The injection molding machine consists of the hopper, screw, the barrel and the injection nozzle of which the main focus is on the screw feeder of the injection molding machine the aim is to design, optimization and analysis of screw feeder to improve the quality of produces parts and obtain higher production rate. The project focus on increasing the fatigue life of screw feeder and to perform FEA analysis Here our main objectives are to increasing the mass flow rate of the granular plastic resin, thus increasing the machine capcity from 7 shots per min to 11 shots per min, to decrease the weakness in the screw feeder which increases the fatigue life of the screw feeder.



Design and Material Selection of Screw Feeder of Injection Molding Machine

To reduce the torsional failure of the screw with proper application of coupling. And improving heat convection through barrel. A step of process of designing of any physical object. for the machine is important task for the good optimizations and result. In the context of design, the main goal of material selection is to minimize cost while meeting product performance goals, it allows to design durability and performance of the product.

II. LITERATURE SURVEY

The repeatability precision of weight for injection molded products is a major technical parameter to measure the quality and precision of injection molded products and evaluate the performance of injection molding machine. The influence of melt temperature, packing pressure, mold temperature and packing time on the weight of microinjection molding products was studied by Taguchi orthogonal experiment. The influence of peak cavity pressure on the weight of products also got analyzed. The experimental results portrays that the packing pressure is the most major process parameter influencing both the weight of the tensile and the impact specimens.[6]

.Reaction injection molding includes polymerization reactor analysis as well as melt injection molding. Processing can be broken down into several unit operations: metering and machine performance, impingement mixing, mold filling, curing and mold design. Commercial RIM machines have been used successfully for non-filler systems. The results are generally satisfactory. Reactants are usually allowed to circulate through the mix head, or even through impingement nozzles, such that uniform temperature control and appropriate agitation of reactants can be obtained. Most heads can switch from the recycle to injection mode under high pressure operation, to minimize the lead/lag problem. The mixing chamber is self-cleaned at the end of each shot by a hydraulically driven piston which pushes out all the residue mixture from the mix head after mold filling. Flow rate/flow area can be adjusted externally by the nozzle size adjuster. Flow rate also can be controlled by the pressure setting. Two or four streams impingement mixing is the common mixing technology used in the present RIM machines. Static or impingement type after-mixers have been used extensively to improve the mixing. Mold filling seems not to be a problem for conventional RIM operation if mold design is appropriate. The typical pressure inside the mold cavity during filling is less than 350 KPa. With the help of slight foaming during curing, RIM polyurethanes usually have excellent, depression-free surfaces. A number of qualitative descriptions of automotive type RIM have appeared, and some basic studies of the process are being carried out. However, as yet there does not appear to be a complete understanding of how the process influences the structure and properties of the polymer formed. The majority of RIM parts have been made in the 140-300 MPa flexural modulus range for fascia applications, where appearance, weight-reduction, and impact resistance are the most important criteria. A representative formulation used to produce automotive fascia by reaction injection molding consists of a polyether/polyester polyol with molecular

weight in the range of 1000-3000, a short chain extender like ethylene glycol, 1,4-butane diol or a diamine and a modified derivative of 1,4-diphenylmethane diisocyanate, MDI. The need for further weight reduction to meet government mileage requirements, and for improved corrosion and impact resistance, makes the extension of RIM materials to other external automotive body components increasingly attractive. For these applications, there will be several new requirements: flexural moduli in the 700-4000 MPa range to provide dimensional stability, but still with the desirable impact strength; a low thermal coefficient of linear expansion to allow satisfactory mating with sheet metal surfaces. An increased thermal stability would also be required for parts that would be painted and baked on the car, or for applications such as hoods with higher in-use thermal exposure.[1]

III. METHODOLOGY

A. General Arrangement Layout

The layout of injection moulding machine was drawn which gave us the overview of the parts and its location in the machine or the system.

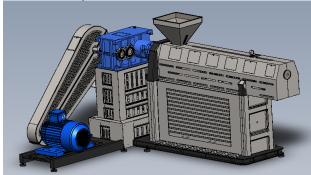


Fig 1:GA layout of Injection Molding Machine

B. Material Selection by Ashby Standard

It is very crucial process involved in any project. As density and strength were important factors so, for this project we selected density vs strength property chart by Ashby.By using Granta software and importing geometry data to it, we were able to find the candidate material.

Table 1- Candidate material and their properties

	Properties			
Material Name	Yield Strength	Tensile Strength	Density (g/cc)	
Low Carbon steel 8620	460	455	7.20	
Carbon Steel 4140	700	1014	4.42	
Carbon Steel 135	851	1100	8.40	
Stainless Steel 304	480	510	2.73	
Stainless Steel 316	276	310	2.70	
Tool Steel H13	425	485	2.80	
D-2 Tool Steel	700	1029	4.68	

It is very necessary to identify the function of the element or part for which the material is to be selected. In this case we aim to improve the torsional strength of the part.





There are three methods for quantitative material selection, they are as follows;

- 1. Cost per Unit Property Method
- 2. Weighted Properties Method
- 3. Digital Logic Method

The properties of the materials are scaled based on the weight factor of the physical property which is also known as the weight factor of the property. The scaled property chart is given below,

Table 2:-Candidate Material and Scaled Properties

	Scaled Properties			
Material Name	Yield Strength	Tensile Strength	Density (g/cc)	
Low Carbon steel 8620	54.05	41.36	85.71	
Carbon Steel 4140	82.256	92.18	52.60	
Carbon Steel 135	100	100	100	
Stainless Steel 304	56.404	46.36	32.5	
Stainless Steel 316	32.432	28.18	32.142	
Tool Steel H13	49.941	44.090	33.33	
D-2 Tool Steel	82.256	93.5454	55.714	

Then, Performance index is calculated for each material. This performance index is then multiplied with the relative cost of that material to get the final material values or say total performance index.

The material with the maximum total performance index is selected as the material for the particular part.

Table 3:-Candidate material and its Relative Cost, **Performance Index and Total Performance** Index

muex					
Material	Relative Cost	Performance Index	Total Performance Index		
Low carbon steel					
8620	2.9	59.319	172.027		
Carbon steel					
4140	6.5	76.512	497.333		
Carbon steel					
135	6.1	100	610		
Stainless steel					
304	2.1	44.25	92.930		
Stainless steel					
316	2.7	30.564	82.525		
Tool steel					
H13	2.5	41.967	104.91		
D-2					
Tool steel	8	78.112	624.901		

Through the table plotted above it is clear that the highest calculated performance index is showed by the material D-2 Tool steel and hence this material is finalized for the screw feeder part of the injection moulding machine.

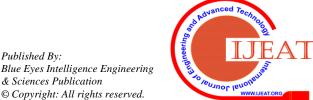
C. Calculations and Designing

There are various calculations involved before we actually start making the part. For designing any part these calculations are very important. With the help of calculations we are able to find the dimensions of the part. Other parameters like flow rate, various temperatures, pressure is found out with help of it

Table 4:-Case Studies of parameters

Description	Case 1	Case 2	Case 3	unit

Description	Case 1	Case 2	Case 3	unit	
INPUT					
Barrel Diameter	0.078	0.09	0.065	m	
Screw lead	0.078	0.09	0.065	m	
Screw speed	210	190	150	rpm	
Number of flights	28	35	21		
Flight width	0.005	0.003	0.004	m	
Channel width	0.025	0.025	0.021	m	
Depth of the feed zone	0.007	0.005	0.004	m	
Conveying efficiency	0.25	0.25	0.25		
Bulk density of polymer	1000	1000	1000	kg/m2	
Length of metering zone	0.201	0.16	0.014	m	
Flight clearance	0.0001	0.00013	0.0000 5	m	
pressure diff. across metering zone	300	300	300	bar	
Melt viscosity	1406	1406	1406	Pa.s	
Density of the melt	1000	1000	1000	kg/m3	
Therml conductivity of the melt	0.174	0.174	0.174	W/(m.k)	
Heat of fusion of the polymer	125.5	125.5	125.5	KJ/kg	
Specific heat of the solid polymer	2.2	2.2	2.2	KJ/(Kg. k)	
Viscosity in the melt film	1406	1406	1406	pa.s	
Barrel temperature	140	140	140	°c	
Meting point of the polymer	75	75	75	°c	
Temperature of the solid polymer	40	40	40	°c	
Density of the solid polymer	1000	1000	1000	kg/m3	
Depth of the feed	0.007	0.007	0.007	m	
Empirical Factor	0.286	0.286	0.286		
Melt viscosity in screw channel	1406	1406	1406	pa.s	
Shear rate in channel	122.5221 135	179.0707 813	127.62 72016	s-1	
channel depth at the outlet	0.003	0.003	0.003	m	
Reciprocal of power exponent	0.5	0.5	0.5		
ratio of channel depths	1	1	1		
factor	15562.97 288	18814.71 676	15883. 89268		
length of the screw zone	1.68	1.24	1.1	m	
Specific heat of melt	2	2	2	KJ/ (Kg.k)	
The flight diameter	0.0778	0.08974	0.0649	m	
vicosity in flight clearance	1400	1400	1400	pa.s	
length of the melt zone	0.201	0.201	0.201		
Diameter	0.15	0.15	0.15	m	
Torque	17810	14500	11200	Nm	
Accelertion due to Gravity	9.81	9.81	9.81	m2/sec	



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Case 1	Case 2	Case 3	unit
7850	7850	7850	kJ/m3
2.1E+11	1.9E+11	2E+11	Pa
1.00E+0	1.00E+0	1.00E+	MPa
3000000	3000000	300000 0	Pa
OUTDI	T		
OUTPU	1		
0.308169	0.308169	0.3081	rad
290.2793 748	277.6477 489	85.506 84199	kg/hr
0.000054	0.000006	0.0000	2/
37266	02243	446371 4	m3/s
195.7415 736	21.68076 552	160.69 37044	kg/h
0.000168 989	3.04868E -05	1.7614 6E-05	m3/s
608.3601 545	109.7525 219	63.412 56822	kg/h
0.321752 784	0.197542 299	2.5340 98664	
0.000403 928	8.52182E -05	9.8073 8E-05	
	179.0707	127.62	
0.857654	0.895353	0.5105	m/sec
0.460760	0.440710	0.1615	m/sec
0.441313	0.493840	0.3598	m/sec
0.260139 11	0.271573 796	0.1548 44709	m/sec
0.000103 673	0.000101 482	0.0001 23132	m
107.5	107.5	107.5	°c
617	617	83525	°c
008	0	000	bar
087	087	00087	m2/s
788.5189 83	890.2427 621	543.80 56235	W/(m2 k)
1.007177	1.003402	1.0029	,
	758 63.93375	14867 27.300	****
44	179	85278	KW
9.505041 688	5.972463 247	4.0495 74567	KW
1.631179 78	0.180673 046	1.3391 14203	KW
72.34930 587	70.08688 809	32.689 54155	KW
2687572 8.94	2188085 7.36	169010 76.03	Pa
2.66E-02	2.98E-02	3.35E- 02	m
0.000259 659	0.000286 992	0.0002 72642	m
2581.683	2335.808	2458.7	bar
14513.81	13805.38	14164.	RPM
012	715	02836	
756000	756000	756000	N
	7850 2.1E+11 1.00E+0 8 3000000 OUTPU 0.308169 071 290.2793 748 0.000054 37266 195.7415 736 0.000168 989 608.3601 545 0.321752 784 0.000403 928 122.5221 135 0.857654 794 0.460760 912 0.441313 52 0.260139 11 0.000103 673 107.5 238.6442 617 403.9740 008 0.000000 087 0.100574 713 788.5189 83 1.007177 812 61.21308 44 9.505041 688 1.631179 78 78 72.34930 587 2687572 8.964 2.66E-02 0.000259 659 2581.683 629 14513.81 012	7850 7850 2.1E+11 1.9E+11 1.00E+0 8 3000000 3000000 OUTPUT 0.308169 0.308169 071 277.6477 748 489 0.000054 0.000006 37266 02243 195.7415 21.68076 736 552 0.000168 3.04868 989 -05 608.3601 109.7525 545 219 0.321752 0.197542 784 299 0.000403 8.52182E 928 -05 122.5221 179.0707 135 813 0.857654 0.895353 794 906 0.460760 0.440710 912 713 0.441313 0.493840 52 553 0.260139 0.271573 11 796 0.000103 0.00101	7850 7850 7850 2.1E+11 1.9E+11 2E+11 1.00E+0 1.00E+0 1.00E+0 8 8 08 3000000 3000000 3000000 OUTPUT 0.308169 0.3081 071 071 69071 290.2793 277.6477 85.506 748 489 84199 0.000054 3000006 0.00006 37266 02243 47 195.7415 21.68076 160.69 736 552 37044 0.000168 3.04868E 1.7614 989 -05 6E-05 608.3601 109.7525 63.412 545 219 56822 0.321752 0.197542 2.5340 784 299 98664 0.000403 8.52182E 9.8073 928 -05 8E-05 122.5221 179.0707 127.62 135 813 72016

With help of 3D CAD software such Solid works the Screw feeder was designed on the basis of basic dimensions to be analysed for further investigation.

D.Analysis

There are various types of analysis carried out on a part. For the Screw feeder we used Finite Element analysis. It reduces the cost of actual prototyping and testing. Number of tests are carried out with help of soft wares to optimize the product and develop it faster.

The software we used for the analysis of the screw feeder is solid works. The parameter applied was torsional force. The result was obtained in the form of stress, strain, displacement and factor of safety.

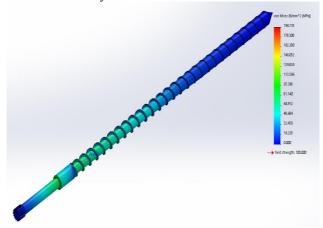


Fig 2: Analysis of the screw feeder for the von misses stress.

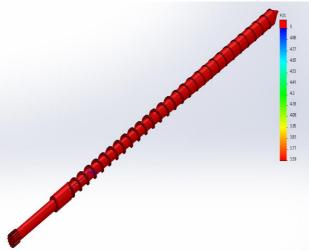


Fig 3: Analysis of the screw feeder for the factor of safety

IV. RESULTS

The material D2 tool steel and carbon steel 135 showed good results through the software. Both the materials showed high torsional strength. However the displacement were same for both the materials.

Table 5:-Candidate Material and its FOS and Yield Strength

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Material	FOS	Yield strength		
Low carbon steel 8620	2.4	460MPa		
Carbon steel 135	4.4	850MPa		
Carbon Steel 4140	3.6	700MPa		

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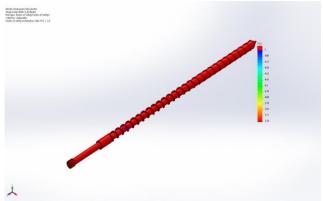


Fig 4:-Analysis of Screw Feeder for D2 Steel(FOS=3.6)

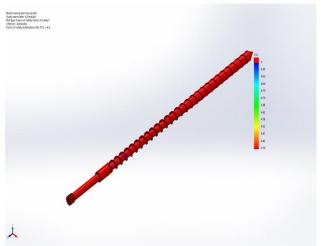


Fig 5:-Analysis of screw feeder for Carbon Steel 135(FOS=4.4)

V. CONCLUSION

The initial design of the screw feeder of the injection moulding was studied and based on that it was redesigned with respect to dimensions and material to gain a control over the output. The capacity of the injection moulding was optimised taking the inputs and constraints into consideration. The analysis was performed on the designed screw feeder to check or verify its functioning under working conditions. It was found out that D-2 Tool steel as a material would be best to select for the screw feeder. The calculations and analysis were successfully completed.

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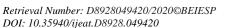
Pranav Karande is an undergraduate research scholar and co-author to this research paper. He is pursuing his graduation in the stream of mechanical engineering at MIT Academy of Engineering, Alandi, India. He has done research work in developing microcontroller based smart helmet kit. He has jointly published research paper on 'Automatic Weighing and Packaging Machine'.



Swarai Gurav is an undergraduate research scholar and co-author to this research paper. He is pursuing his graduation in the stream of mechanical engineering at MIT Academy of Engineering, Pune, India.He has worked on developing an agriculture automation bot and also worked on research base analysis of Electrocalescenes by using non uniform electric field.



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